Spindle PositioningSpindle positioning system specifications -Option on all OmniTurns.

Spindle power: Voltage: Resolution: Max Speed: Min Speed:	5HP 200 - 230V 3 phase or single phase (contact the factory for wiring) .02 4000 rpm standard, 5000 optional .004 rpm	
M19	programmed by itself causes the spindle to position via the shortest route to 0 . After the command is executed the spindle is locked in position. To release the spindle use M05 . This is a one shot command, is modal.	
CI(-)nnn.nn	This makes the spindle move an incremental amount of degrees.	
CA(-) <i>nnn.nn</i> This makes the spindle move to an absolute location of degrees.		
Snnn.nn	The "S" number if programmed along with a M19 indicates the spindle speed in RPM. With no sign the spindle will rotate in the M03 direction. The "-" sign will cause the spindle to rotate in the M04 direction.	
G35/G36 - (see notes in G33 section on use and formats)	<i>Extra course long-lead ipr feeds.</i> The G35 allows long lead ipr feeds. G35 sets Max feed rates to 1 ipr. G36 cancels G35. When G35 is active the system resolution drops to .00025". G35 may be activated any time. There is also a G35F2 mode for 2"/rev feeds. Please refer to the threading section for details on format and use.	
	After G35 and G36 there must be a G92 command	
	<i>NOTE:</i> Both axes must be returned to the position they were in when the G35 was invoked before G36 is programmed. G35 must be canceled before a tool change!	
Notes on use: • Before a spindle posi	tioning in absolute command can be executed there must be a M19 command t	

• Before a spindle positioning in absolute command can be executed there must be a M19 command to orient the spindle.

• Be sure that you calculate the amount of C needed for a coordinated C and Z move. In the following example there is not enough C given to complete the Z move, the slide will then hang up. A solution would be to increase C to 432 to complete the Z move.

Formula to find number of degrees needed = the distance travel \div IPR x 360

Z0 G35 G92X0Z0 G95F.25

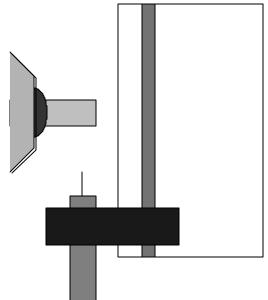
Spindle Positioning

C360Z-.3S5 G94F50Z0 G36 G92X0Z0

X.75Z1 Z-.3

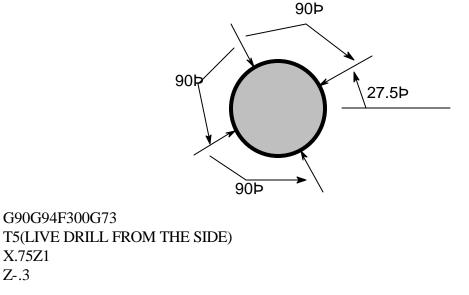
• Currently there is no feedback from the spindle drive that a move to a location has been completed. When you rotate the spindle into position you will have to put a dwell after a rotation command to allow it time to complete the move.

Example showing positioning and cross drilling



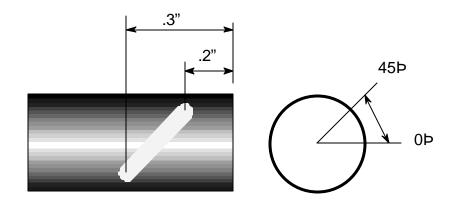
In the following example we show a drill mounted on the slide.

The slide will be used to drill the holes. We will drill (4) holes 90 apart, the first hole is located at 27.5 from a reference 0 .



Spindle Positioning		
M15(TURN DRILL ON)		
M19	ORIENT THE SPINDLE TO 0	
CA27.5	GOES TO 27.5 ABSOLUTE	
LS4	START OF LOOP	
G94F1X.5	DRILL A HOLE	
X.75F300		
CI90	ROTATE 90 INCREMENTALLY	
G04F1	DWELL TO ALLOW SPINDLE TO ROTATE	
LF	END OF LOOP	
Z3		
M30		

An example showing rotational milling



Here the cutter will go into the material and then make a combined C and Z move to create a slot. G90G94F300G73 T5(LIVE DRILL FROM THE SIDE) X.75Z1 Z-.2 G35 COARSE RESOLUTION MODE ON G92X.75Z-.2 USER DEFINED M TO START LIVE TOOL M15(TURN DRILL ON) M19 ORIENT THE SPINDLE TO 0 X.5F1 G95F.8 CA-45Z-.3S3.5 MILL WHILE MOVE 45 ROTATION AND .1" IN Z X.75F300 M16 USER DEFINED M TO STOP LIVE TOOL Z-.2 NOTE THAT THIS WAS THE STARTING LOCATION G36 G92X.75Z-.2 G00Z2 M30

Spindle Positioning